

## Rotary actuator fail-safe for zone valves

- Torque motor 1 Nm
- Nominal voltage AC/DC 24 V
- Control modulating 2...10 V
- Position feedback 2...10 V
- Snap-assembly of the actuator
- Flow setting variable
- Deenergised closed (NC)



## Technical data

<b>Electrical data</b>	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	2.5 W
	Power consumption in rest position	0.5 W
	Power consumption for wire sizing	5 VA
	Connection supply / control	Cable 1 m, 4x 0.34 mm <sup>2</sup>
	Parallel operation	Yes (note the performance data)
<b>Functional data</b>	Torque motor	1 Nm
	Operating range Y	2...10 V
	Input impedance	100 kΩ
	Position feedback U	2...10 V
	Direction of motion fail-safe	fix deenergised closed (end stop NC = 0%)
	Manual override	with actuator (clicked out)
	Running time motor	75 s / 90°
	Running time fail-safe	60 s / 90°
	Sound power level, motor	35 dB(A)
	Sound power level, fail-safe	35 dB(A)
	Position indication	Mechanical
	Flow setting	see product features
<b>Safety data</b>	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)
	Degree of protection IEC/EN	IP40
	EMC	CE according to 2014/30/EU
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Type of action	Type 1.AA
	Rated impulse voltage supply / control	0.8 kV
	Pollution degree	2
	Ambient humidity	Max. 95% RH, non-condensing
	Ambient temperature	5...40°C [41...104°F]
	Storage temperature	-40...80°C [-40...176°F]
	Servicing	maintenance-free
<b>Weight</b>	Weight	0.18 kg
<b>Terms</b>	Abbreviations	POP = Power off position / fail-safe position PF = Power fail delay time / bridging time

**Safety notes**



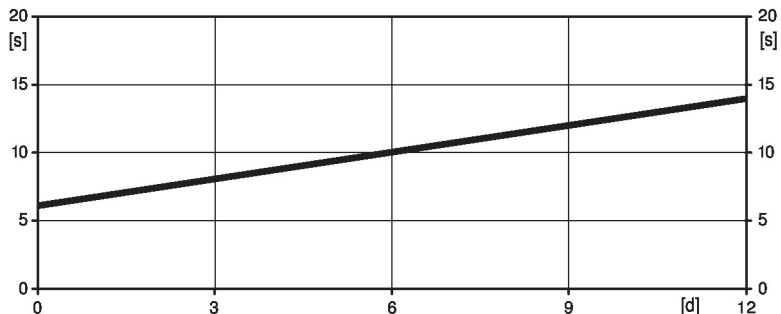
- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

**Product features**

**Operating mode** The actuator moves the valve to the desired operating position at the same time as the integrated capacitors are loaded. The measuring voltage U serves for the electrical display of the actuator position 0...100% and as control signal for other actuators.  
 Interrupting the supply voltage causes the valve to be moved to the fail-safe position by means of stored electrical energy, taking into account the bridging time (PF) of 1 s set at the factory.

**Pre-charging time (start up)** The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of a power failure, the actuator can move at any time from its current position into the fail-safe position. The duration of the pre-charging time depends mainly on how long the power was interrupted.

Typical pre-charging time



[d] = Power failure in days  
 [s] = Pre-charging time in seconds

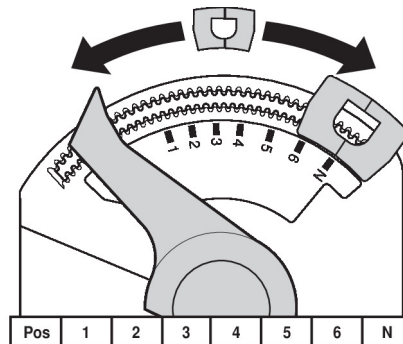
**Delivery condition (capacitors)** The actuator is completely discharged after delivery from the factory, which is why the actuator requires approximately 25 s pre-charging time before initial commissioning in order to bring the capacitors up to the required voltage level.

**Simple direct mounting** Tool-free snap assembly.  
 The actuator can be plugged on the valve by hand (Caution! Just vertical movements). Pins must match the holes on the flange.  
 The mounting orientation in relation to the valve can be selected in 180° increments. (Possible two times)

**Manual override** Click out the actuator and rotate the valve spindle with the help of the actuator.

**Product features**

- Adjustable angle of rotation** The angle of rotation of the actuator can be changed by clip in 2.5° increments. This is used to set the maximum flow rate of the valve.
- High functional reliability** The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
- Flow setting** Adjustable Kv values (C2..Q-.., C4..Q-..) / V'max values (C2..QP(T)-..) are given in the respective zone valve data sheets.  
 2-way valve: Remove end stop clip and place at desired position.  
 3-way valve: Remove end stop clip (change-over application).  
 After every change of the flow setting by means of end stop clip, an adaptation must be triggered on the modulating actuators.



**Accessories**

Mechanical accessories	Description	Type
	Spindle extension CQ	ZCQ-E
	End stop clip, Multipack 5 pcs.	ZCQ-C
	End stop clip, Multipack 20 pcs.	Z-ESCM

**Electrical installation**

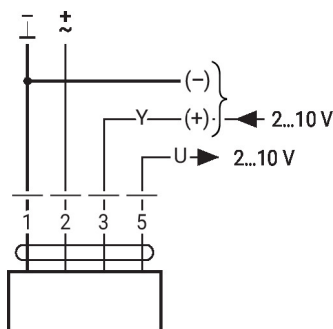


Supply from isolating transformer.  
 Parallel connection of other actuators possible. Observe the performance data.

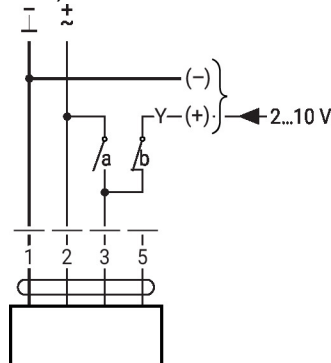
**Wire colours:**

- 1 = black
- 2 = red
- 3 = white
- 5 = orange

AC/DC 24 V, modulating



Override control (frost protection circuit)



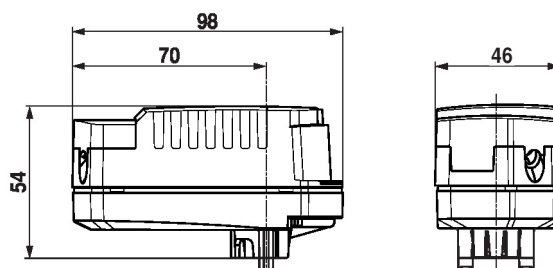
1	2	3 (a)	3 (b)	Valve Symbol
				A - AB = 100%
				A - AB = 0%
			2 V	A - AB = 0%
			10 V	A - AB = 100%

## Operating controls and indicators


**1 Push-button**

Press button: Triggers angle of rotation adaptation, followed by standard mode

## Dimensions



## Further documentation

- The complete product range for water applications
- Data sheet for zone valves
- Installation instructions for zone valves and actuators
- General notes for project planning